

Entropy and Information Gain Notes

Entropy:

- Entropy provides a measurement of uncertainty associated with a random variable or random process.

Note: This is the definition of entropy under/in the context of information theory.

- For a discrete r.v. X with possible outcomes X_1, X_2, \dots, X_n which occur with probability $P(X_1), P(X_2), \dots, P(X_n)$, the entropy of X , denoted as $H(X)$, is defined as:

$$H(X) = - \sum_{i=1}^n P(X_i) \log_2 P(X_i)$$

Note: $H(X) = E[-\log_2 P(X)]$, where E is expected value.

- Note: When $P(X_i) = 0$, for some X_i , we take $P(X_i) \log_2 P(X_i)$ to be 0, which is consistent with its limit.

I.e. $\lim_{p \rightarrow 0} p \log(p) = 0$

- E.g. Suppose we flip a fair coin.

$$P_1 = P_2 = \frac{1}{2}$$

$$H(X) = - \left(\frac{1}{2} \log_2 \left(\frac{1}{2} \right) \right)$$

$$= - \log_2 \left(\frac{1}{2} \right)$$

$$= - (\log_2(1) - \log_2(2))$$

$$= - (-1)$$

$$= 1$$

- E.g. Say we toss an unfair coin now.
Suppose the probability of getting heads is 70%.
Then, the entropy becomes:

$$H(X) = - \sum_{i=1}^n P(X_i) \log_2 P(X_i)$$

$$= - (0.7 \cdot \log_2(0.7) + 0.3 \cdot \log_2(0.3))$$

$$\approx 0.8816 \leftarrow \text{Since one side comes up more frequently, there is reduced uncertainty and hence entropy.}$$

- E.g. The entropy of rolling a fair die is:

$$H(X) = - \sum_{i=1}^n P(X_i) \cdot \log_2 P(X_i)$$

$$= - \cancel{(6)} \left(\frac{1}{6} \right) \left(\log_2 \left(\frac{1}{6} \right) \right)$$

$$= - \left(\log_2(1) - \log_2(6) \right)$$

$$= \log_2(6)$$

$$= 2.58 \leftarrow \text{Since the probability of rolling a die } \left(\frac{1}{6} \right) \text{ is smaller than the prob of flipping a coin } \left(\frac{1}{2} \right), \text{ its entropy will be higher.}$$

- We also have **conditional entropy**.

$$- H(X|Y) = - \sum_{i,j} P(X_i, Y_j) \log_2 P(X_i | Y_j)$$

$$= - \sum_j P(Y_j) \sum_i P(X_i | Y_j) \log_2 P(X_i | Y_j)$$

$$= \sum_j P(Y_j) H(X|Y_j)$$

Mutual Information:

- **Mutual information** is a measure of the info shared by 2 r.v.'s.
I.e. It is a measure of how much about the state of one such var is known when it is conditioned on the state of the other.
- $I(x; y) = H(x) - H(x|y)$
 $= H(y) - H(y|x)$
- Also called **information gain**.